

Asymmetric Linearizable Local Reads

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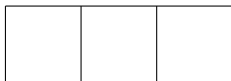
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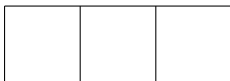
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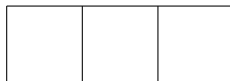
Follower



Leader (🏰)



Follower



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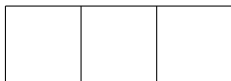
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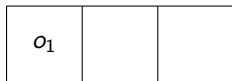
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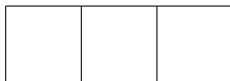
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Follower

o_1		
-------	--	--

Leader (👑)

o_1		
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Follower

o_1		
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✓ o_1		
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o_1		
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Follower

q1		
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Leader (🏰)

q1		
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Follower

q1		
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Follower

o ₁ ✓		
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Leader (🏰)

o ₁ ✓	o ₂	
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Follower

o ₁ ✓	o ₂	
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Leader (🏰)

o ₁ ✓	o ₂	
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Follower

o ₁ ✓	o ₂	
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Leader (🏰)

o ₁ ✓	o ₂ ✓	
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Follower

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Follower

q1	q2	
----	----	--

Leader (🏰)

q1	q2	
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Follower

q1	q2	
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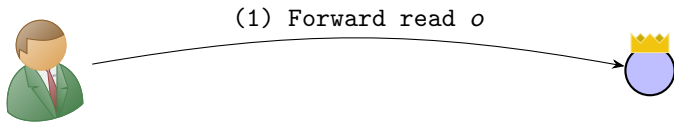
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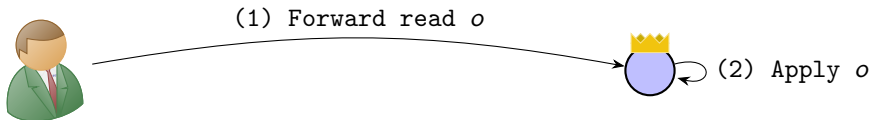
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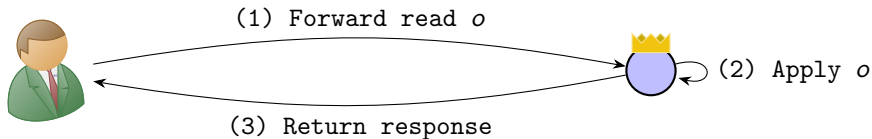
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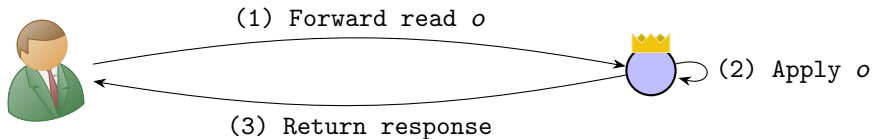
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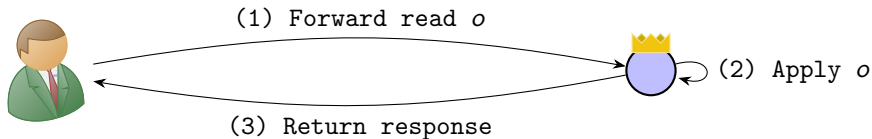
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- ✗ When the leader is in another datacenter read latency can be **100s of milliseconds!**

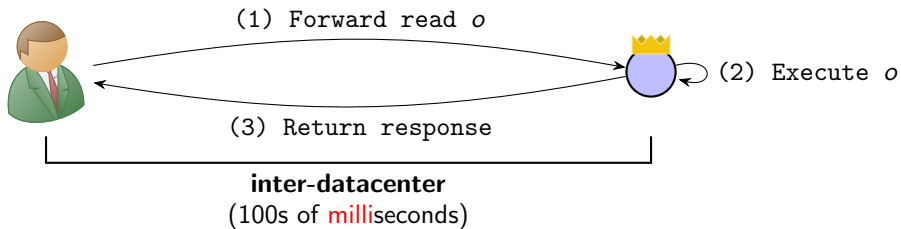
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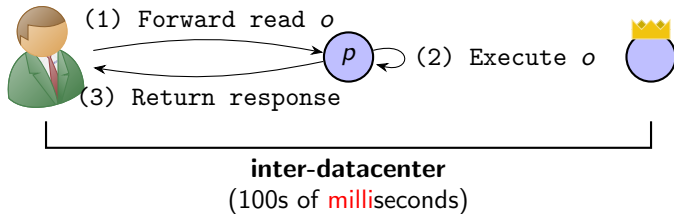
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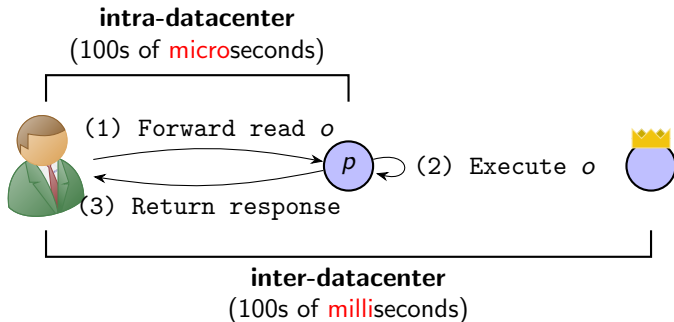
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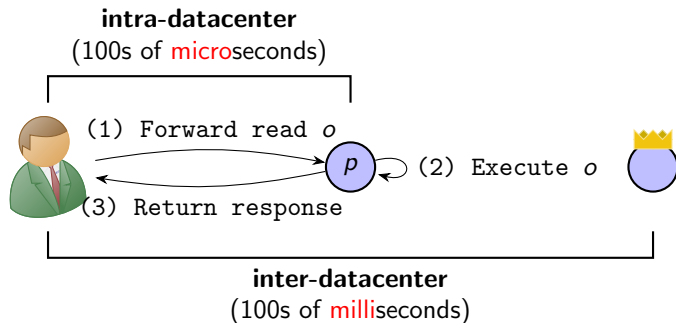
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- In the best case read latency is reduced by **orders of magnitude!**

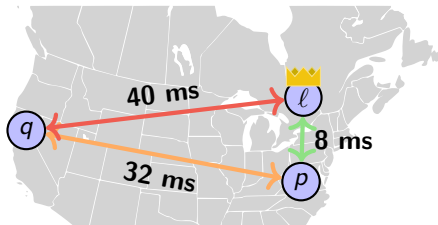
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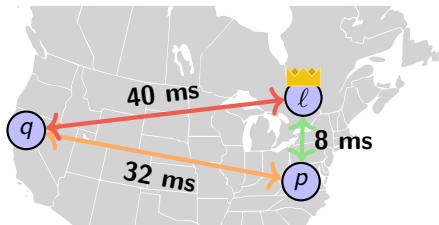
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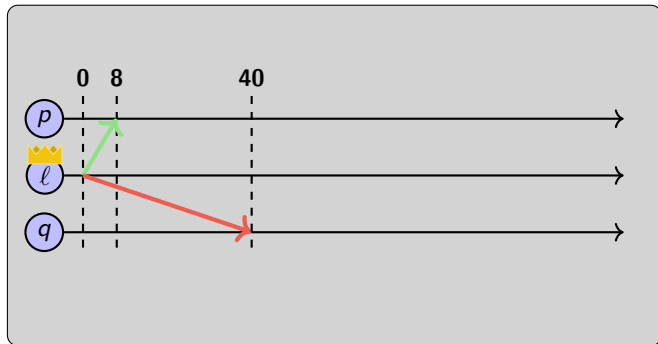
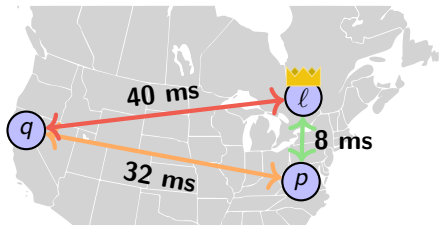
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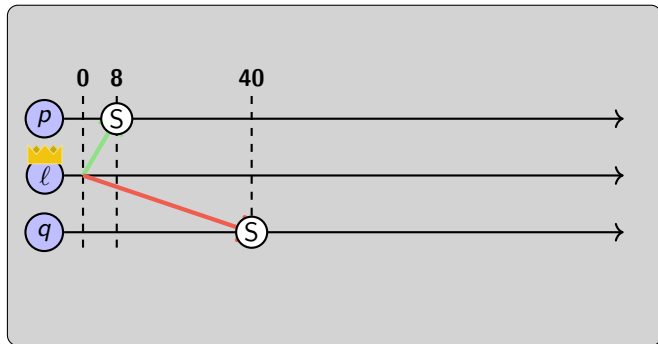
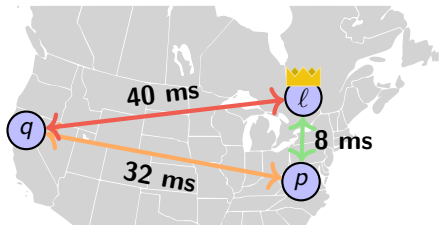
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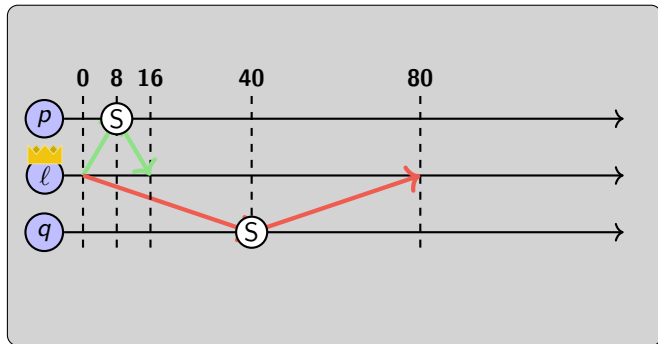
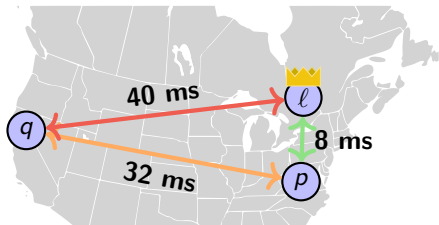
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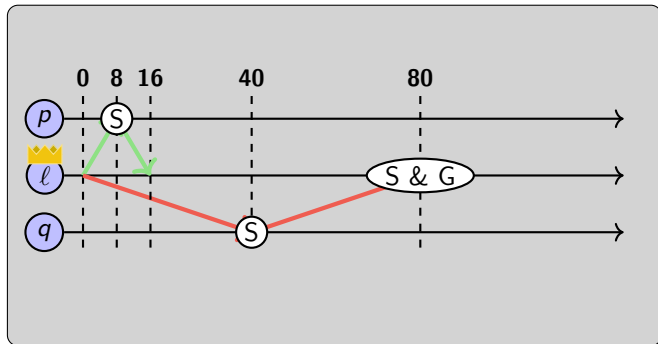
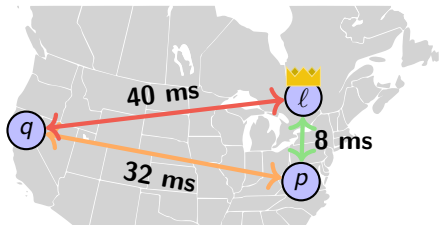
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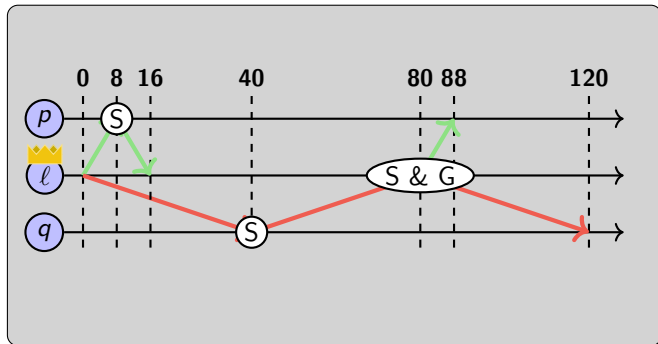
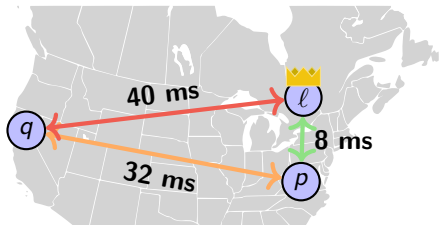
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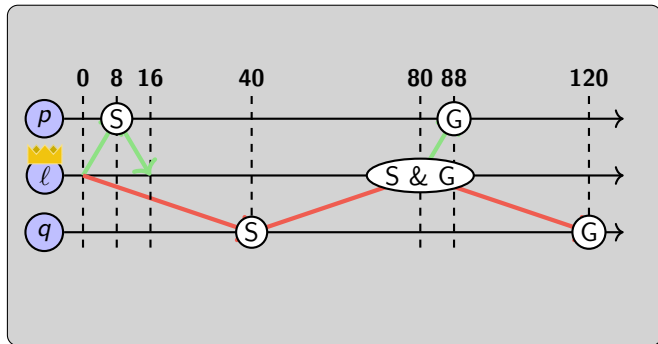
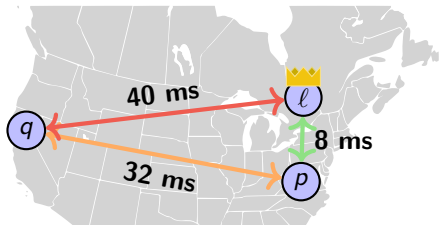
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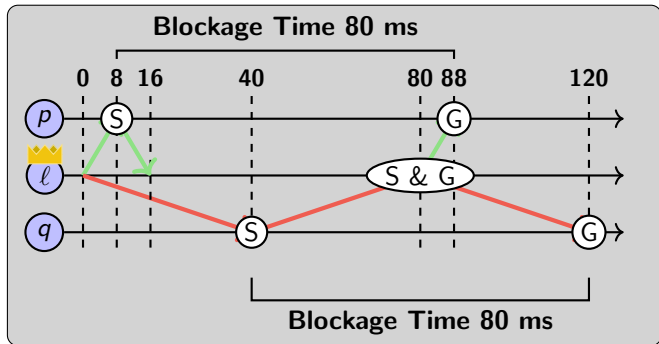
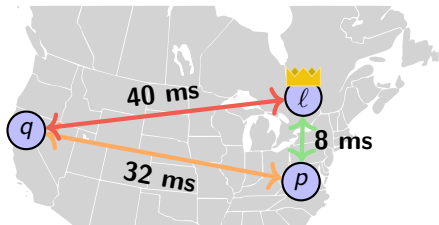
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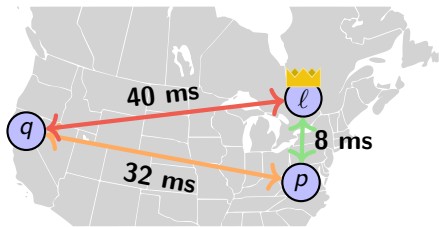
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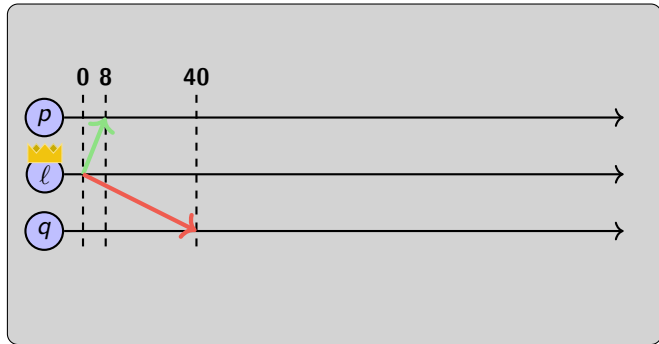
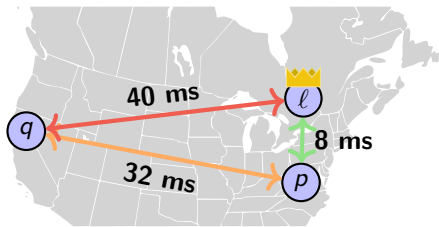
- ▶ During fault-free periods with fixed message delays, reads can block for **80 ms**.

The State-Of-The-Art (“Delayed Stamping”)

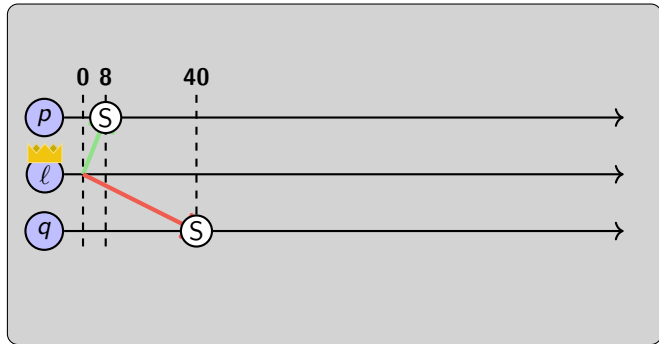
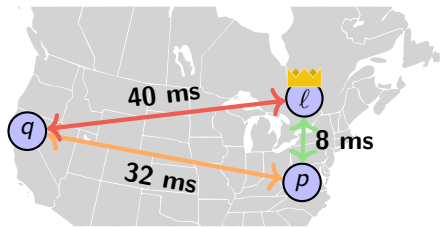
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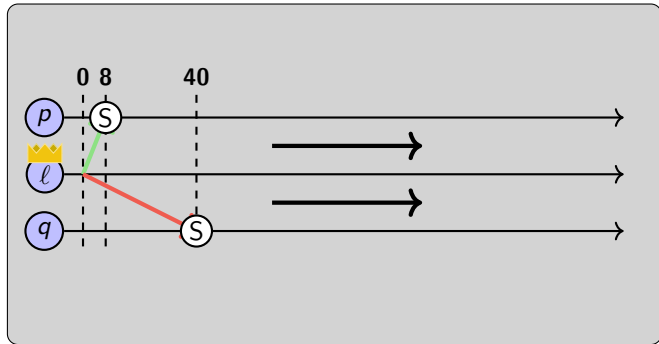
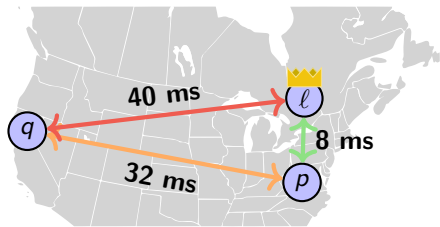
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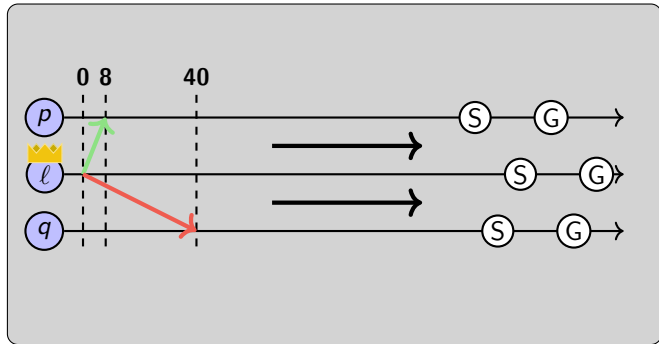
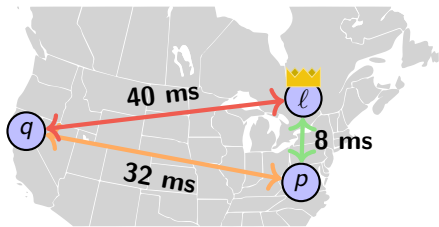
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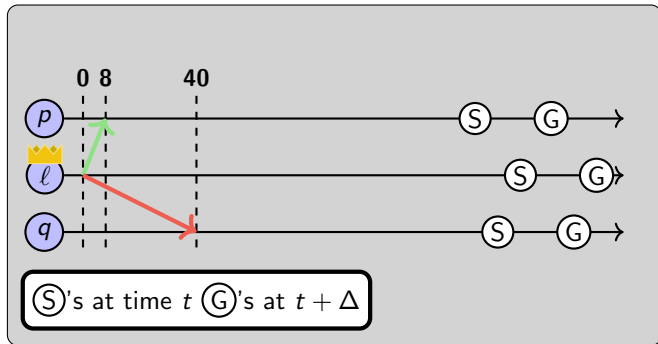
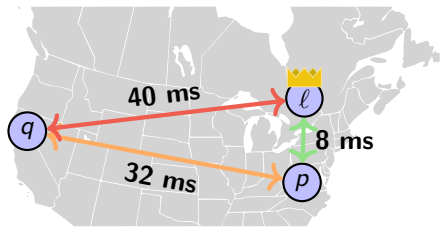


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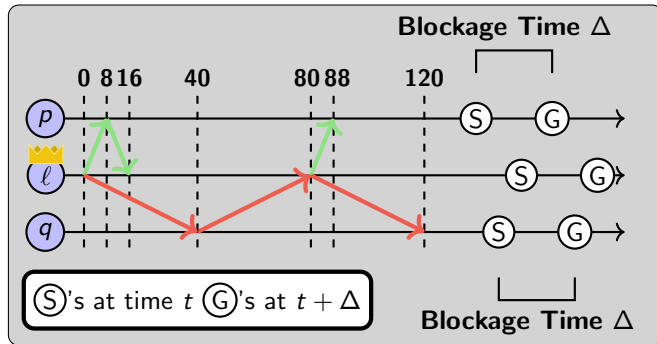
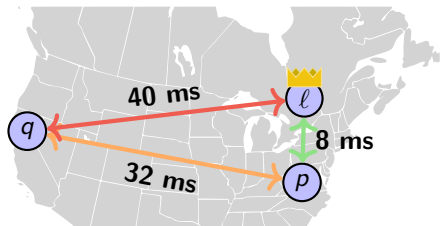
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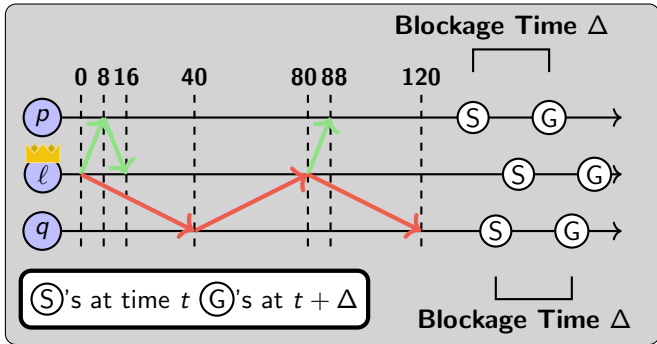
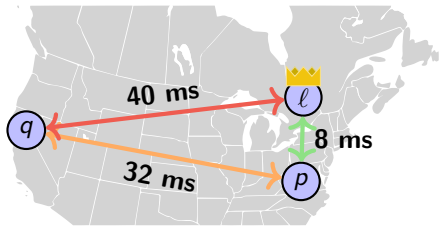
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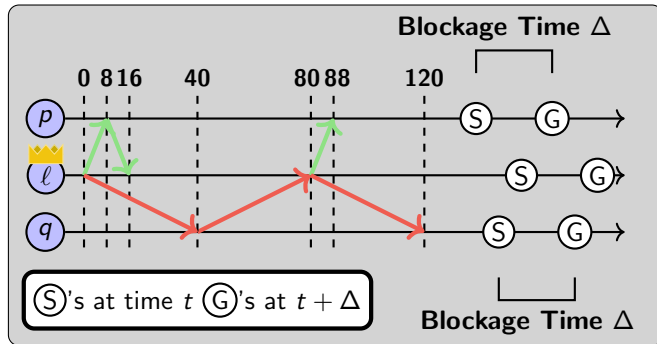
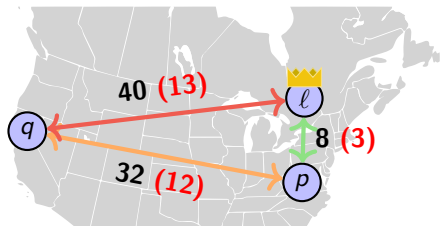
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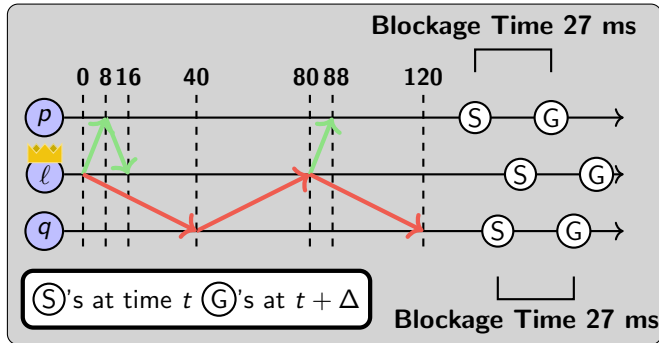
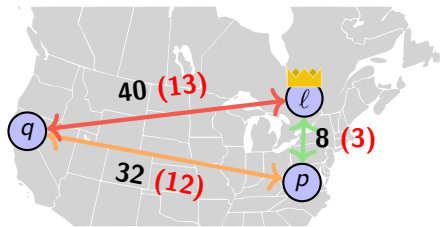
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- Without specialized clock synchronization hardware (e.g. Truetime), $\Delta \geq 27$ ms.

Can lower blockage times be achieved?

This Work: Lower Blockage Times by Leveraging Network Asymmetry

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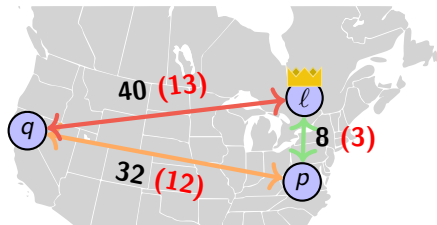
- ▶ Two new local reads algorithms that reduce worst-case blockage times at followers:

1. close to the leader, or
2. close to the network's center.

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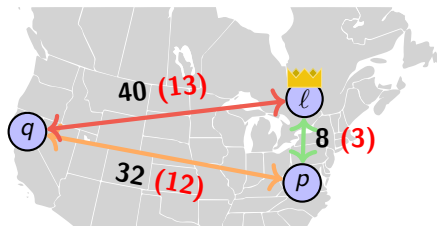


	Blockage Time @ p	Blockage Time @ q
Eager Stamping	80 ms	80 ms
Delayed Stamping	27 ms	27 ms

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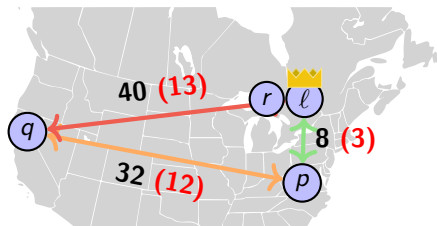


	Blockage Time @ p	Blockage Time @ q
Eager Stamping	80 ms	80 ms
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Pairwise-Leader (ours)	10 ms	54 ms

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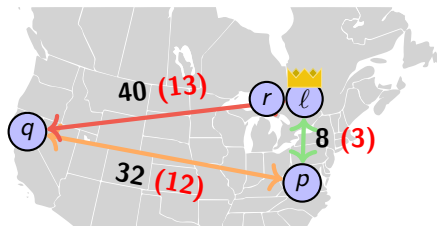


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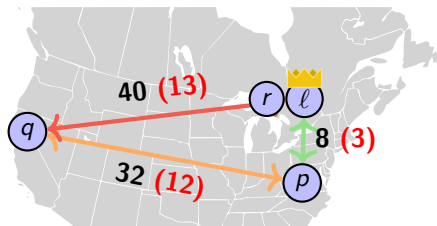


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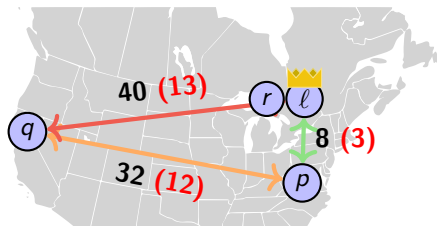


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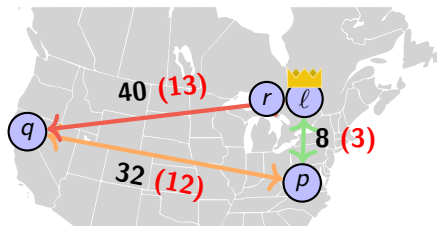


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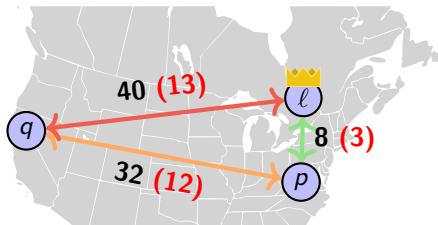
Pairwise-Leader

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- ▶ **Core idea:** schedule $\textcircled{S}$ and $\textcircled{G}$ using a pairwise event scheduling primitive instead of globally synchronized clocks (like Delayed Stamping algorithms do).

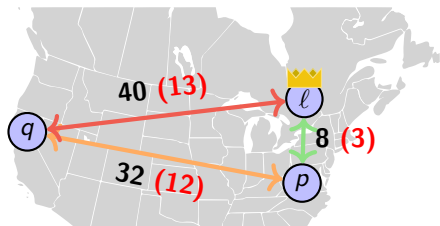
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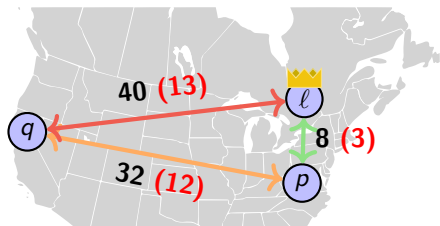


Event Structure

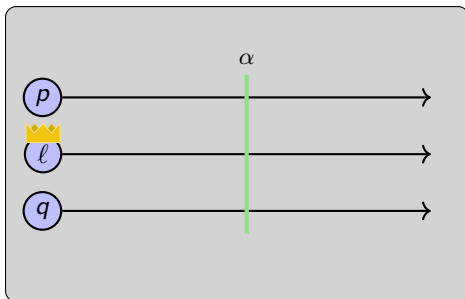


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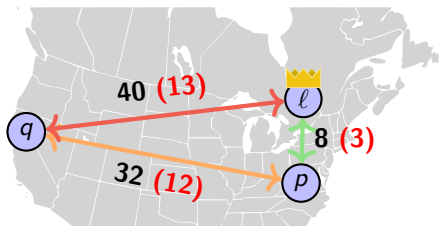


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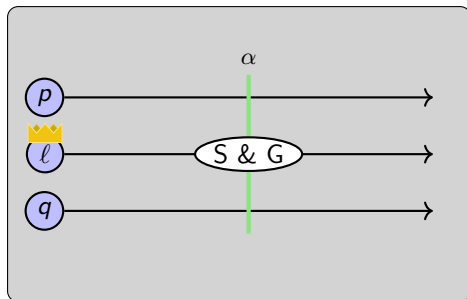


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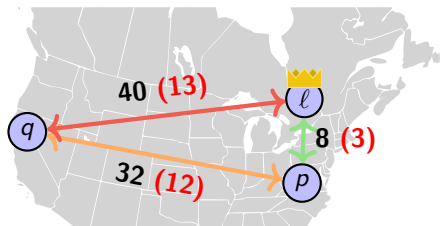


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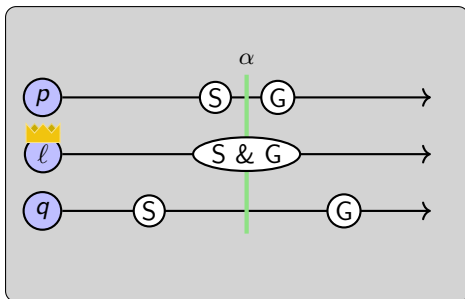


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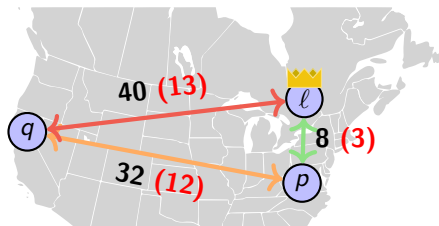


Event Structure

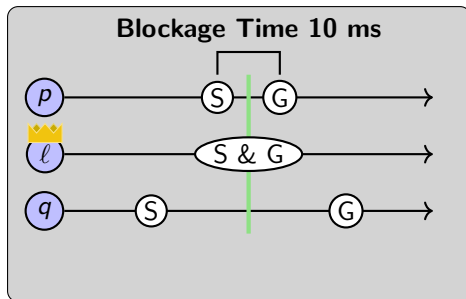


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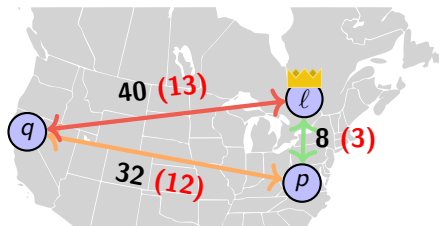


Event Structure

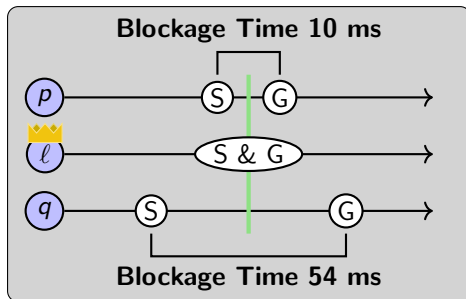


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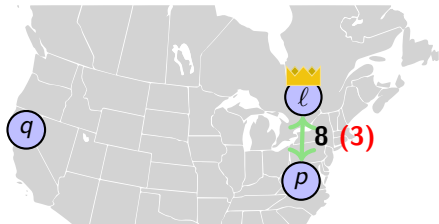


Event Structure



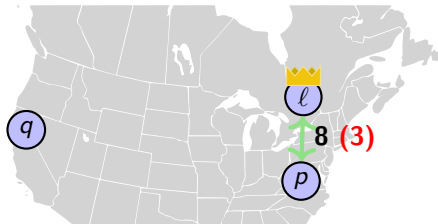
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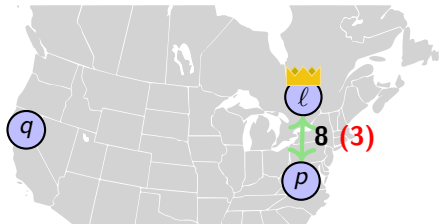
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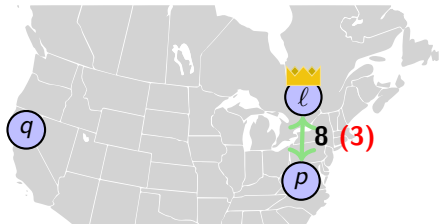


Marker establishment

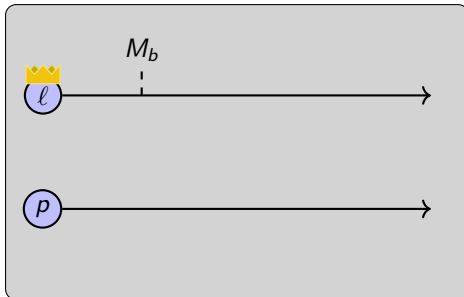


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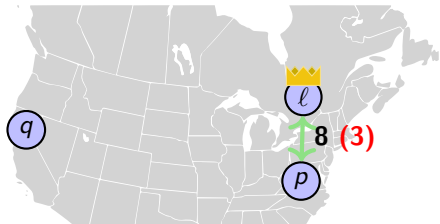


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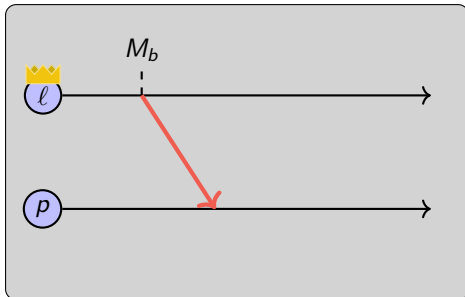


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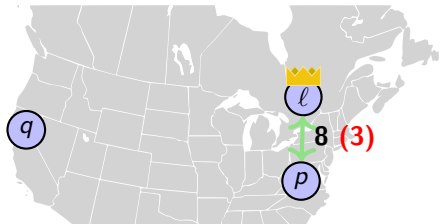


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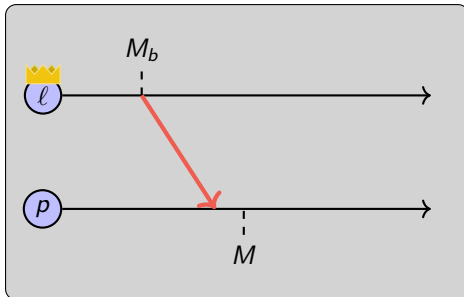


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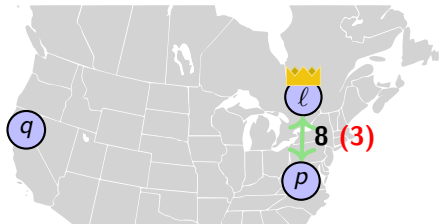


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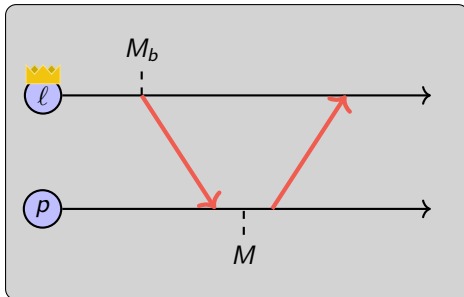


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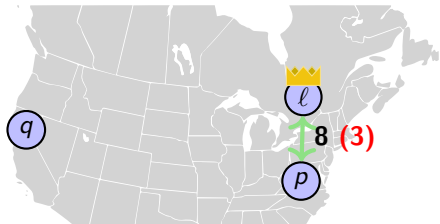


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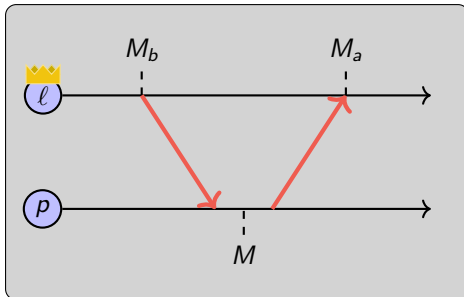


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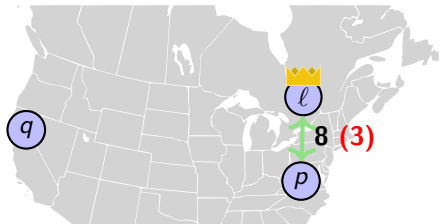


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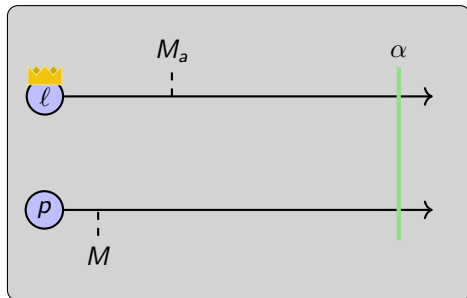


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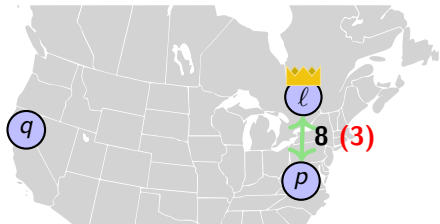


Scheduling $\textcircled{S}$ on p

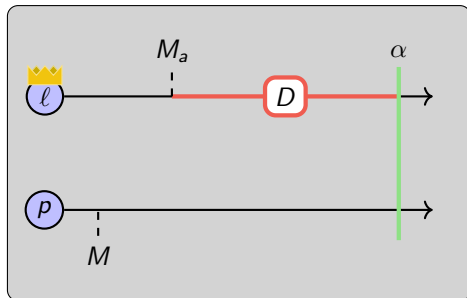


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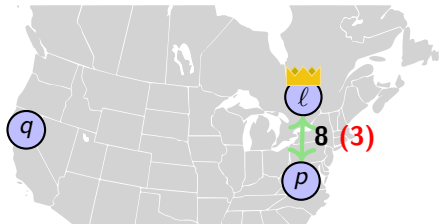


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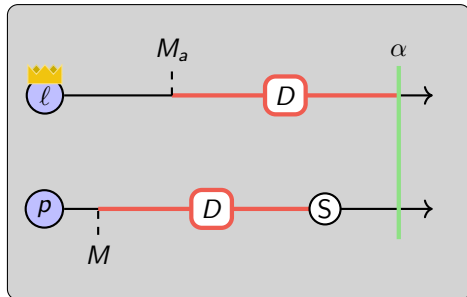


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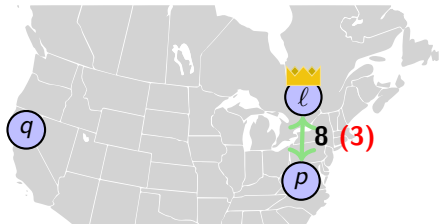


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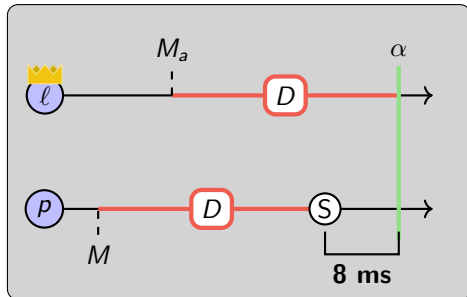


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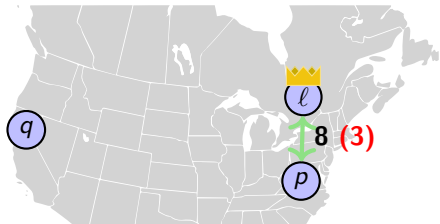


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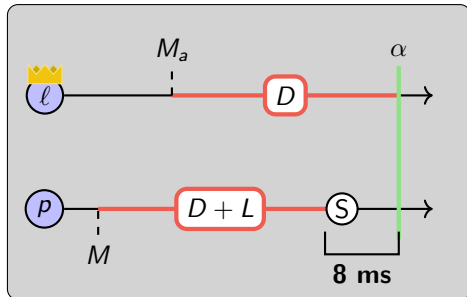


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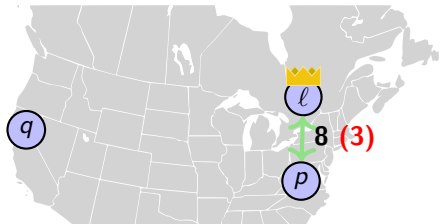


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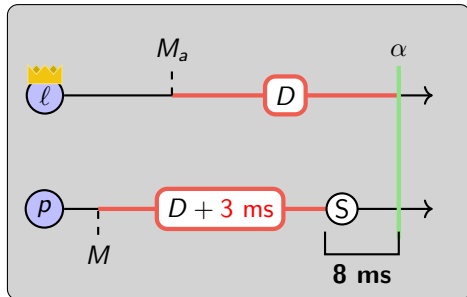


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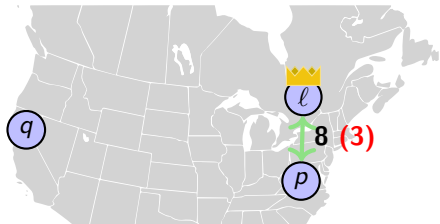


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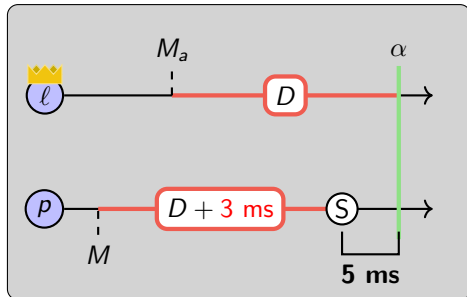


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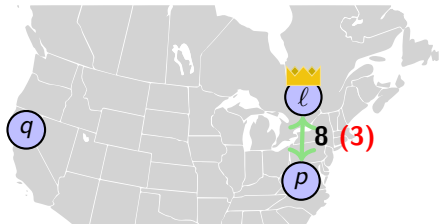


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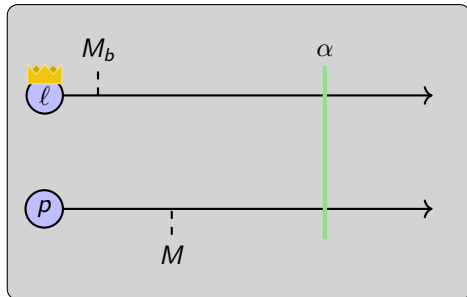


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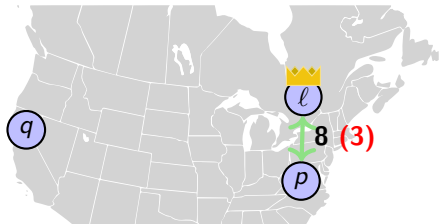


Scheduling $\textcircled{G}$ on p

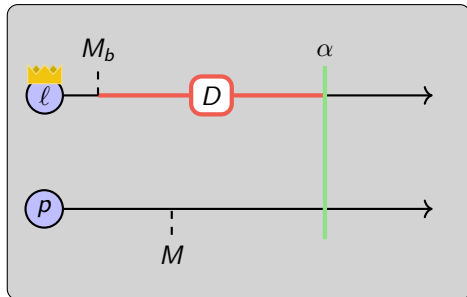


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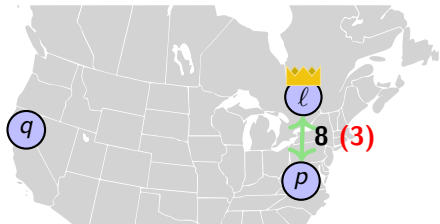


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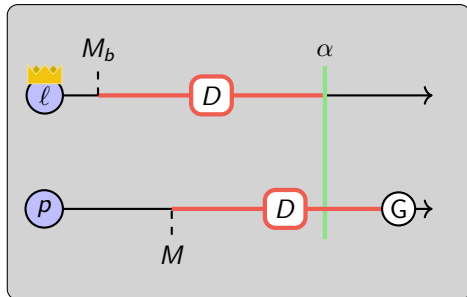


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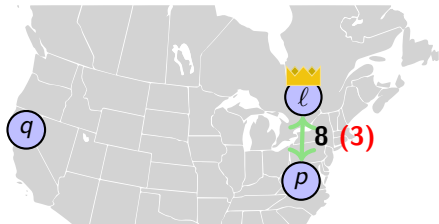


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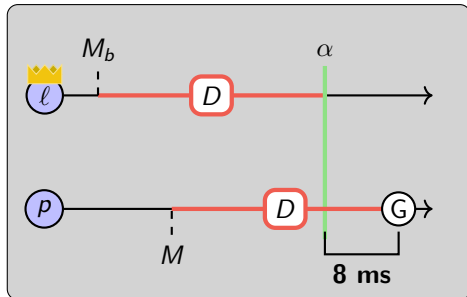


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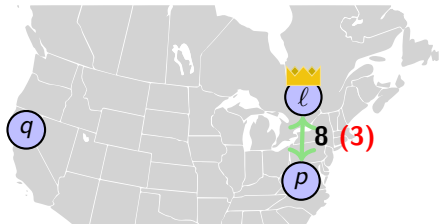


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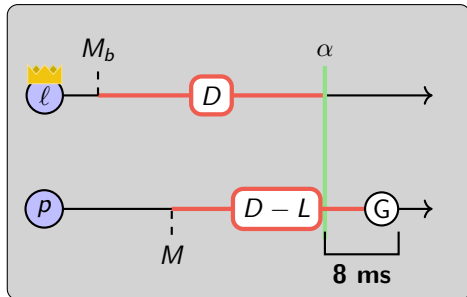


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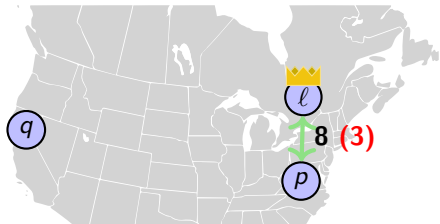


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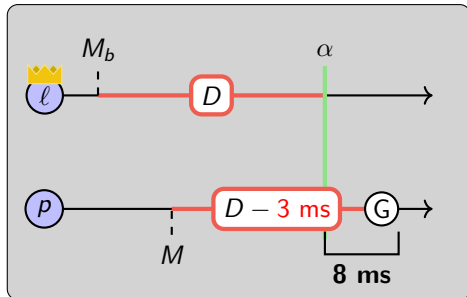


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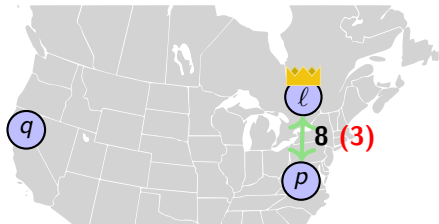


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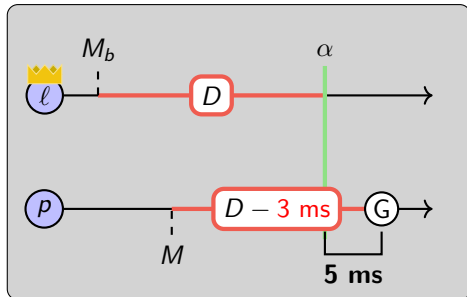


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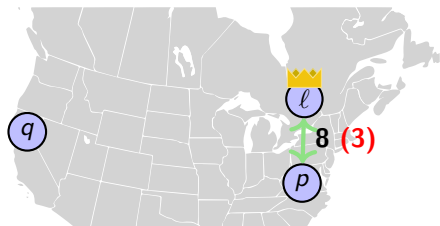


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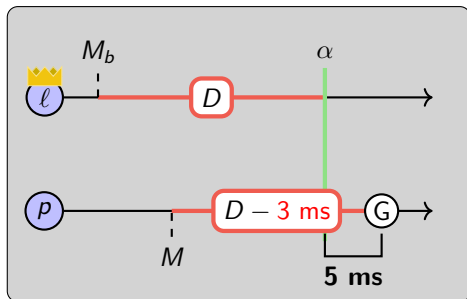


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Scheduling $\odot$ on p



- Can tolerate at most ϵ drift by scaling $D + L$ and $D - L$ proportionally to ϵ .

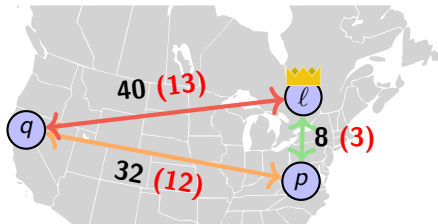
Pairwise-Leader Summary

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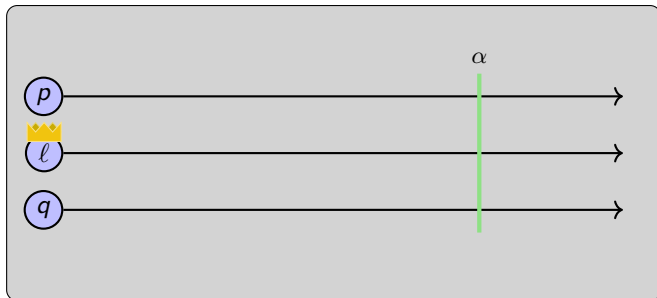
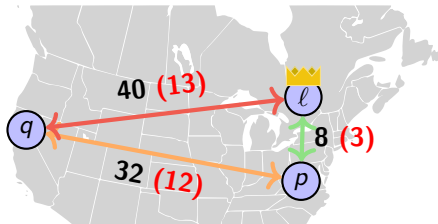
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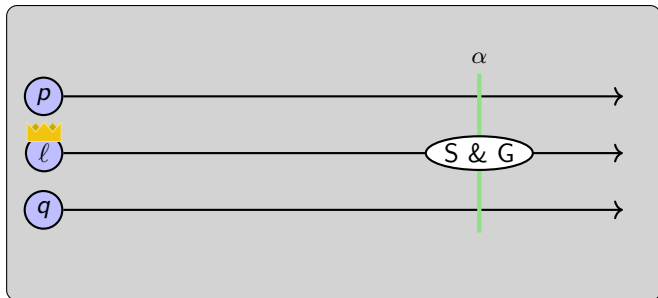
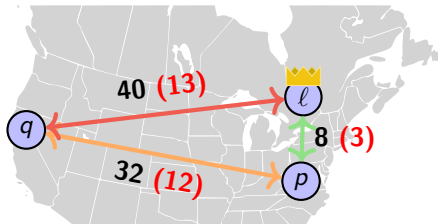
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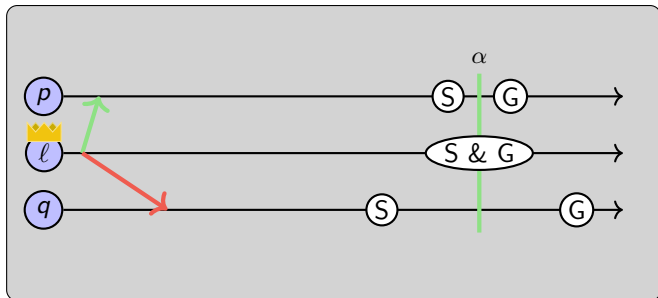
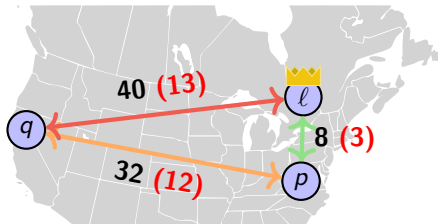
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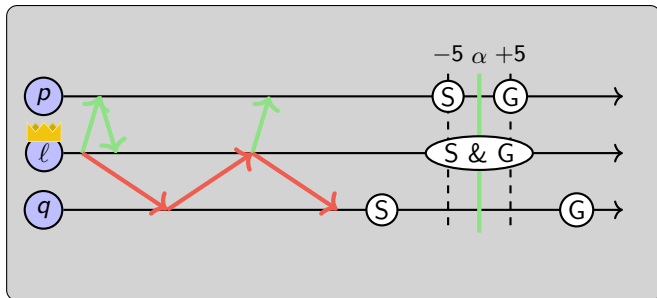
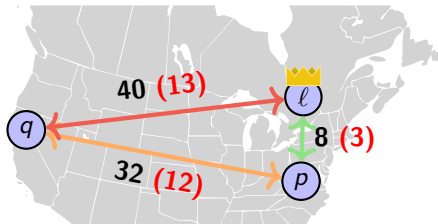
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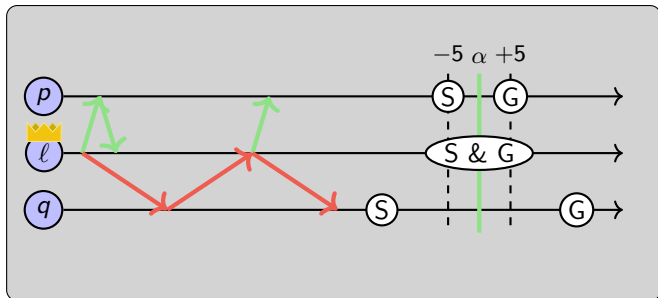
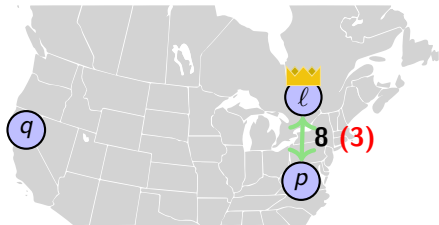
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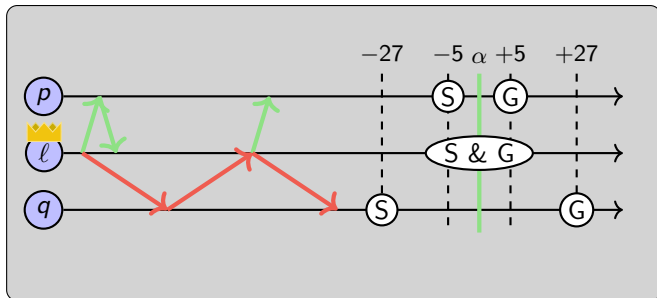
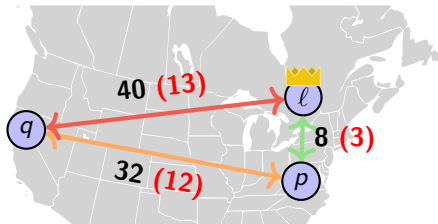
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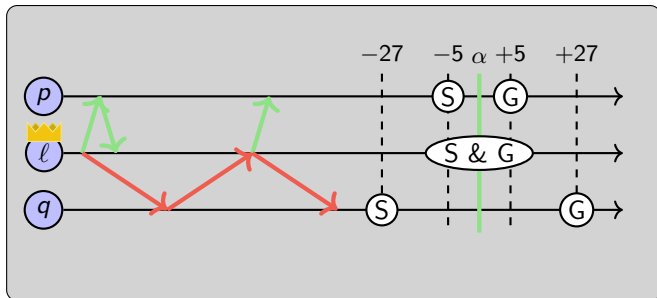
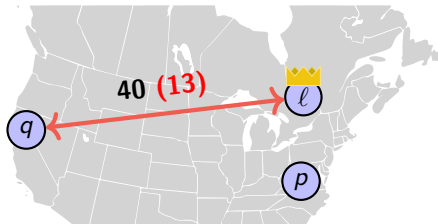
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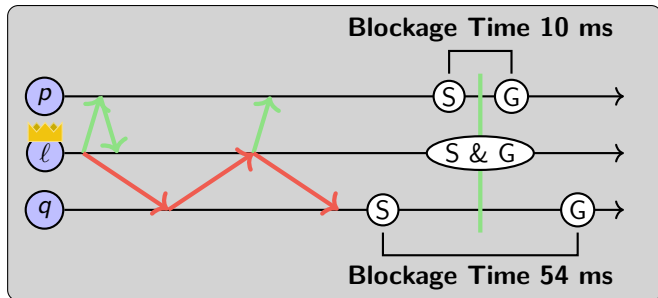
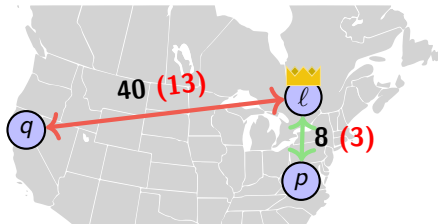
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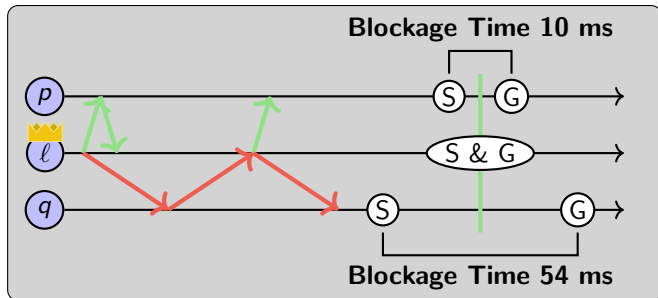
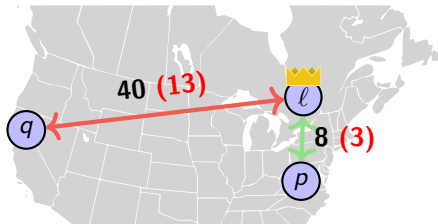
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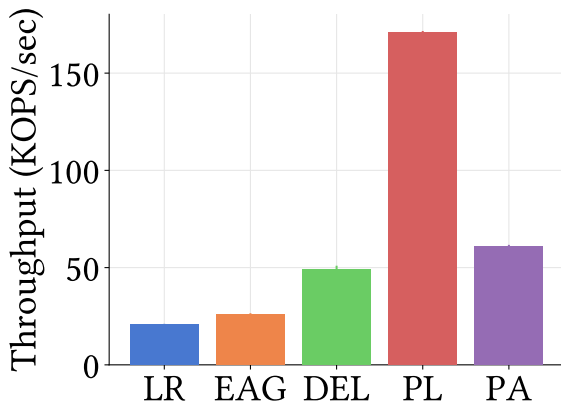
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- Blockage time is the RTT minus $2 \times \text{LB}$ between a follower and the leader (👑).

Benefits in RocksDB

- ▶ Geo-distributed RocksDB deployment spanning 5 AWS regions spread across North America and Europe.
- ▶ 5 replicas per region each running a YCSB workload.



Takeaways

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1. Local read algorithms provide near zero read latency at all replicas in the best-case, but reads need to block for some time in the worst-case.
2. Existing local read algorithms suffer from **large symmetric** blockage times.
3. Our work overcomes this by presenting two new local read algorithms that achieve **asymmetric** blockage times through *pairwise event scheduling*.

Thank you!

Questions

mthiessen@cs.toronto.edu

Paper

